## Answer all questions.

<b>Q1.</b> a) Write "T" for true and "F" for false for each of the following statements.	5
<ul> <li>An <i>in-place</i> planar convex hull algorithm takes memory to store the input points and an additional O(1) memory for working space.</li> <li>A cube is 5-equiprojective.</li> </ul>	
<ul> <li>Dual of a triangulation produced by Graham's scan is Hamiltonian.</li> </ul>	
• Lower bound of comparison based sorting is at most $O(n)$ since the Jordan sorting can be done in linear time.	1
• Power diagram is a variation of polygon triangulation.	
b) Prove an <i>O</i> ( <i>n</i> log <i>n</i> ) lower bound of computing the convex hull in 2D. Why does this lo bound also hold in 3D?	ower 5
<b>Q2.</b> Describe Chan's output-sensitive algorithm for computing the convex hull in 2D. Als derive the time complexity.	so 10
Q3. a) Prove that the dual of a triangulation of a simple polygon without any hole is a tree	ee. 5
b) Explain with an example that for a simple polygon with <i>n</i> vertices, $\lfloor n/3 \rfloor$ cameras are sometimes necessary to guard the polygon.	5
<ul><li>Q4. a) Prove that the size of a Voronoi diagram is linear?</li><li>b) Explain the relation between convex hull in 3D and Delaunay triangulation in 2D<sup>4</sup></li></ul>	5
How can you use this relation to find an algorithm for computing the Delaunay triangulation in 2D?	? 5